# On the complexity of freezing automata networks of bounded pathwidth

Eric Goles, Pedro Montealegre, Martín Ríos-Wilson, G. Theyssier

CNRS, AMU, Institut de Mathématiques de Marseille

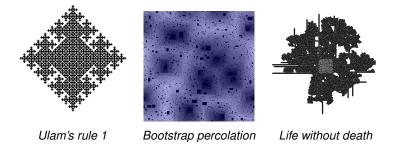
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### Freezing cellular automata

- global map  $F: Q^{\mathbb{Z}^d} \to Q^{\mathbb{Z}^d}$
- *Q* endowed with some order ≤
- freezing property:  $\forall c \in Q^{\mathbb{Z}^d}, \forall z \in \mathbb{Z}^d : F(c)_z \leq c_z$

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#### **Theorem (Ollinger-Theyssier, 2021)**

	1D freezing CA	2D freezing CA
nilpotency	decidable	undecidable
prediction	NL	P-complete
trace	undecidable	undecidable

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**nilpotency:** all orbits converge to the same fixed point

- prediction problem: given finite init. conf. and time t what is the value of cell 0 at time t?
- trace problem: given finite patterns u and v, is there an orbit from [u] to [v]?

$$[u] = \{ c \in Q^{\mathbb{Z}^d} : c_{|D} = u \}$$
 where  $u : D \subseteq \mathbb{Z}^d 
ightarrow Q$ 

Blondel-Delevenne-Kůrka's universality in dynamical systems

# Freezing automata networks

• G = (V, E) a graph

• local maps:  $\delta_{v} : Q^{N^{-}(v)} \to Q$  / global map:  $F : Q^{V} \to Q^{V}$ 

**Q** endowed with some order  $\leq$ 

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Theorem (Goles-Montealegre-Rios-Theyssier, 2021)

- freezing AN of bounded degree and bounded treewidth have a NC trace specification problem
- hardness results otherwise
- trace specification problem: given a set of allowed traces at each node v, is there an orbit such that the trace at each node is allowed?

nilpotency/prediction/reachability reduce to trace problem

# Trace properties vs. logic on orbits

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**FO**<sup>+</sup>: first order logic with predicates  $\rightarrow$  and  $\rightarrow^+$ 

# Finite vs. infinite 1D freezing

finite "1D" AN  $\equiv$  bounded degree and bounded pathwidth

recap of complexity results

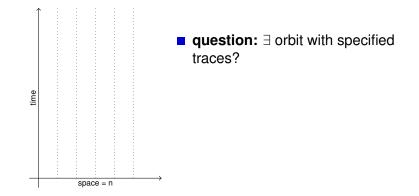
	Infinite 1D CA	Finite "1D" AN	
Nilpotency	Undecidable / Decidable	PSPACE-complete / ?	
Trace properties	Undecidable / Undecidable	PSPACE-comp. / ?	
FO <sup>+</sup>	Undecidable / ?	PSPACE-complete / ?	
(how to read the table: general case / freezing case)			

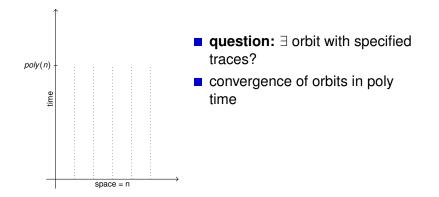
# Finite vs. infinite 1D freezing

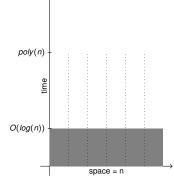
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recap of complexity results + our contributions:

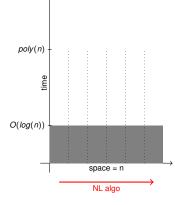
	Infinite 1D CA	Finite "1D" AN	
Nilpotency	Undecidable / Decidable	PSPACE-complete / co-NL	
Trace properties	Undecidable / Undecidable	PSPACE-comp. / NL-comp.	
FO <sup>+</sup>	Undecidable / ?	PSPACE-complete / NP-hard	
(how to read the table: general case / freezing case)			





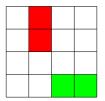


- question: ∃ orbit with specified traces?
- convergence of orbits in poly time
- succinct representation of traces

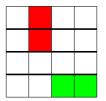


- **question:** ∃ orbit with specified traces?
- convergence of orbits in poly time
  - succinct representation of traces
- NL algorithm:
  - guess traces from left to right
  - check adjacent traces

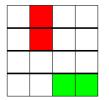
reduction from 2D tiling problem



reduction from 2D tiling problemlayout on a line

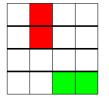




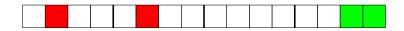


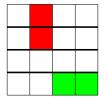
- reduction from 2D tiling problem
- layout on a line
- 1 valid orbit = check 1 vertical domino





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- reduction from 2D tiling problem
- layout on a line
  - 1 valid orbit = check 1 vertical domino
- valid tiling = fixed point with only accepting valid orbits towards it
- technical: FO<sup>+</sup>characterization of validity

