

# **Automata networks**

## **3 short stories**

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# Overview

**Finite** and  
**multicomponent**  
*dynamical system*

**Distributed**  
*computational device*  
with **bounded memory**

- McCulloch and Pitts (1940s)
- gene interaction networks
- social interaction networks
- distributed computing, graph automata
- memoryless computation
- network coding

# Plan

- 1** Finite maps
- 2** Labeled graphs
- 3** Succinct graphs

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# Finite maps

- $Q$  finite alphabet

## Definition

An automata network is a **map**  $F : Q^n \rightarrow Q^n$  for some  $n$ .

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- $x, F(x), F^2(x), F^3(x), \dots$  is an **orbit**.

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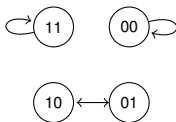
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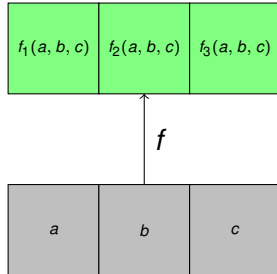
- $x \in Q^n$  is a **configuration**,
- $x, F(x), F^2(x), F^3(x), \dots$  is an **orbit**.
- **Example**: swapping Boolean registers

$$\sigma : \{0, 1\}^2 \rightarrow \{0, 1\}^2$$
$$\sigma(a, b) = (b, a)$$



# Instructions, sequentialization

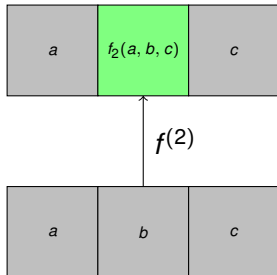
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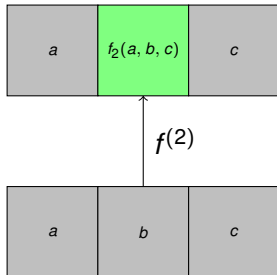
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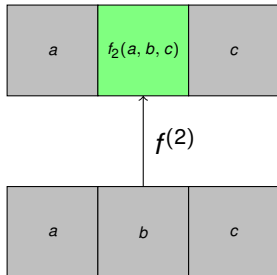
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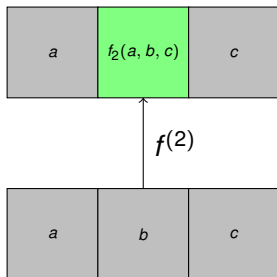
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- $\langle \sigma \rangle_{\text{Seq}} = ?$

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- $\sigma(a, b) = (b, a)$
- $\langle \sigma \rangle_{\text{Seq}} = \{id; \sigma^{(1)}; \sigma^{(2)}\}$

## What map can be sequentialized?

- say  $g$  is **sequentialized** by  $f$  if  $g \in \langle f \rangle_{\text{Seq}}$
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  - $\oplus$ : addition mod 2
  - $f(a, b) = (a \oplus b, a \oplus b)$
  - $(a, b) \xrightarrow{f^{(1)}} (a \oplus b, b) \xrightarrow{f^{(2)}} (a \oplus b, a) \xrightarrow{f^{(1)}} (b, a)$

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## Theorem (Cameron-Fairbairn-Gadouleau, 2014)

$\exists f \in F(Q^n)$  such that  $B(Q^n) \subseteq \langle f \rangle_{\text{Seq}}$  (unless  $n = |Q| = 2$ ).

- $B(Q^n)$ : bijections  $Q^n \rightarrow Q^n$
- $F(Q^n)$ : maps  $Q^n \rightarrow Q^n$



## What map can be sequentialized?

- the following  $g \in F(\{0, 1\}^2)$  is **not** sequentializable:

$$00 \mapsto 01 \mapsto 11 \mapsto 10 \mapsto 00$$

- **F. Bridoux** by computer search: any  $g \in F(\{0, 1\}^3)$  is sequentializable

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### Theorem (Bridoux-Gadouleau-Theyssier, 202?)

For any  $n \geq 5$  **any**  $g \in F(\{0, 1\}^n)$  is sequentializable.

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An automata network is a **finite graph labeled** by local maps

$$\delta_v : Q^{N^-(v)} \rightarrow Q$$

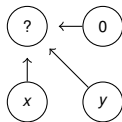
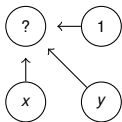
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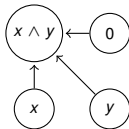
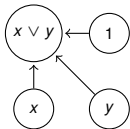
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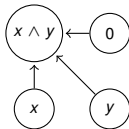
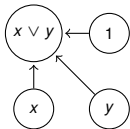


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- majority networks are **universal**, in particular:
  - $\exists$  transients and cycles of **exponential** length
  - reachability ( $y \in \text{Orbit}(x)$ ?) is **PSPACE-complete**



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- what about majority on **unoriented** graphs?

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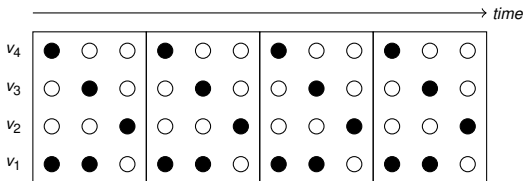
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- much more is known (threshold rules, infinite graphs, etc)

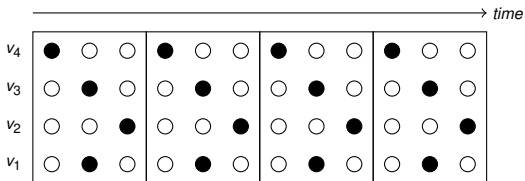
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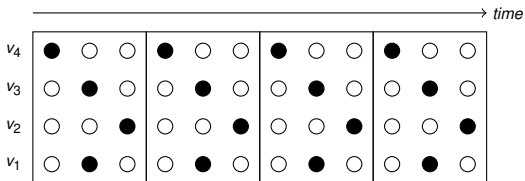
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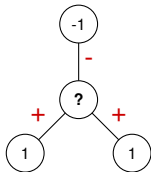
## Theorem (Goles-Montealegre-Salo-Törmä, 2016)

**Undirected** majority networks under **bloc sequential** schedules are **universal**.

- NB: sequence of updates of constant period is enough

## On the edge of universality

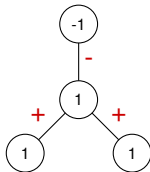
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- ponderation  $\pm$  on edges
- $\delta_v =$  ponderated minimum





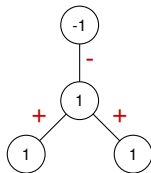
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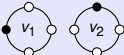
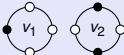
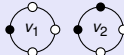





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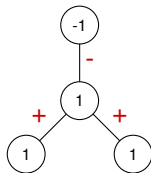


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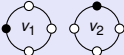
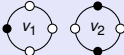
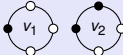



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	$\leq Cst$ $\leq Cst$ $NC_0$	<b>universal</b>	<b>universal</b>	<b>universal</b>
	$\leq poly$ $\leq poly$ PTIME	$\leq poly$ $\leq poly$ PTIME	<b>universal</b>	<b>universal</b>
	$\leq poly$ $\leq poly$ NP	$\leq poly$ $\leq poly$ NP	$\leq poly$ $\leq poly$ NP	$\leq poly$ <b>superpoly</b> NP

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## Orbit graphs

- many automata network questions on their orbit graphs
- $F(x) = y \iff (x, y)$  is an edge

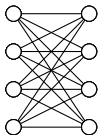
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### Definition

A **non-deterministic** automata network is a **directed graph** represented **succinctly** by a Boolean circuit  $C(x, y)$  computing its adjacency relation.

- vertices are identified by labels:  $x, y \in \{0, 1\}^n$
- size of the graph:  $N \leq 2^n$



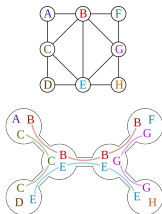
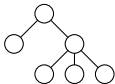
- $N = 2^n$
- $C(x, y) = \begin{cases} 1 & \text{if } x_1 \neq y_1, \\ 0 & \text{else.} \end{cases}$

# Recall: Courcelle's theorem

## Theorem (Courcelle, 1990)

Any MSO formula can be tested in linear time on graphs of bounded treewidth.

- treewidth:



- monadic second order logic (MSO), e.g. 3-colorability:

$$\exists X_1, X_2, X_3, \forall v, \left( \bigvee_i v \in X_i \right) \wedge \left( \forall v', \bigwedge_i \neg(\text{adj}(v, v') \wedge v \in X_i \wedge v' \in X_i) \right)$$

## Succinct graph property testing

- For some property  $\mathcal{P}$  of graphs:
  - **input:**  $N$  and circuit  $C(x, y)$
  - **question:** does the graph  $G_{N,C}$  satisfy  $\mathcal{P}$ ?



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## Theorem (Gammard-Guillon-Perrot-Theysier, 202?)

Any non-trivial MSO property on **bounded treewidth succinct** graphs is either NP-hard or co-NP-hard.

- non-trivial  $\equiv \infty$  models and  $\infty$  counter-models of treewidth  $\leq k$
- Remark: determinism  $\implies$  bounded treewidth orbit graph

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## Theorem (Gammard-Guillon-Perrot-Theysier, 202?)

There are non-trivial MSO property on **succinct** graphs which are **neither** NP-hard **nor** co-NP-hard (under reasonable complexity assumption).

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